

SIP-adus Workshop 2018

SIP-adus Field Operational Test

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SIP-adus International Cooperative WG

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SIP-adus Workshop 2018

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1. Large-scale FOT
2. FOT regional activities
3. Next Step

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1. **Large-scale FOT**
2. FOT regional activities
3. Next Step

Steps to the Goal

2014

2015

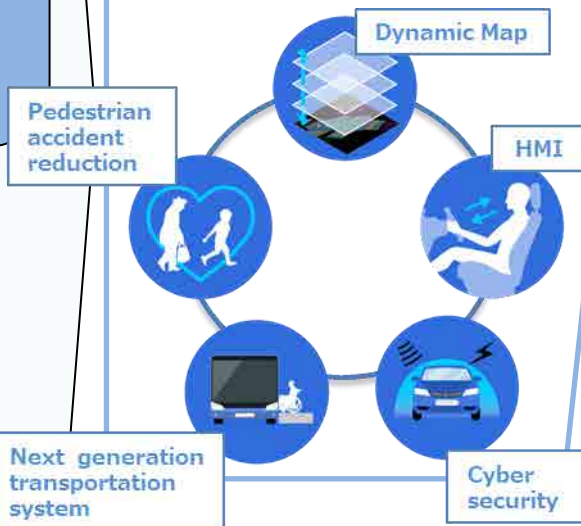
2016

2017

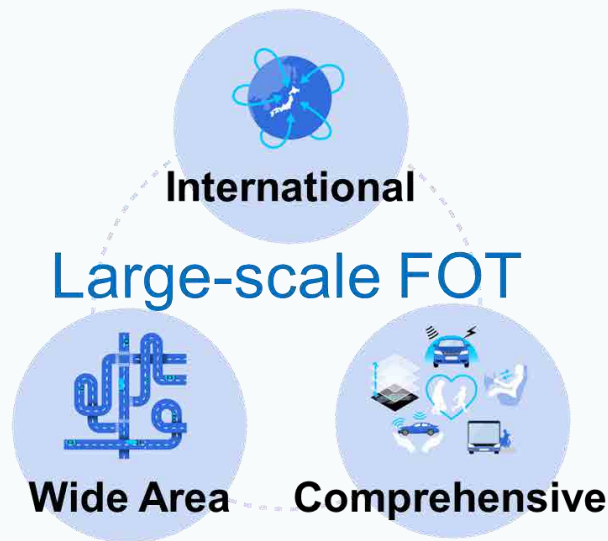
2018

- ◆ Framework Construction
- ◆ Investigation for various R&D theme

- ◆ Integration into 5 major R&D theme activity



- ◆ Final step to the Goal



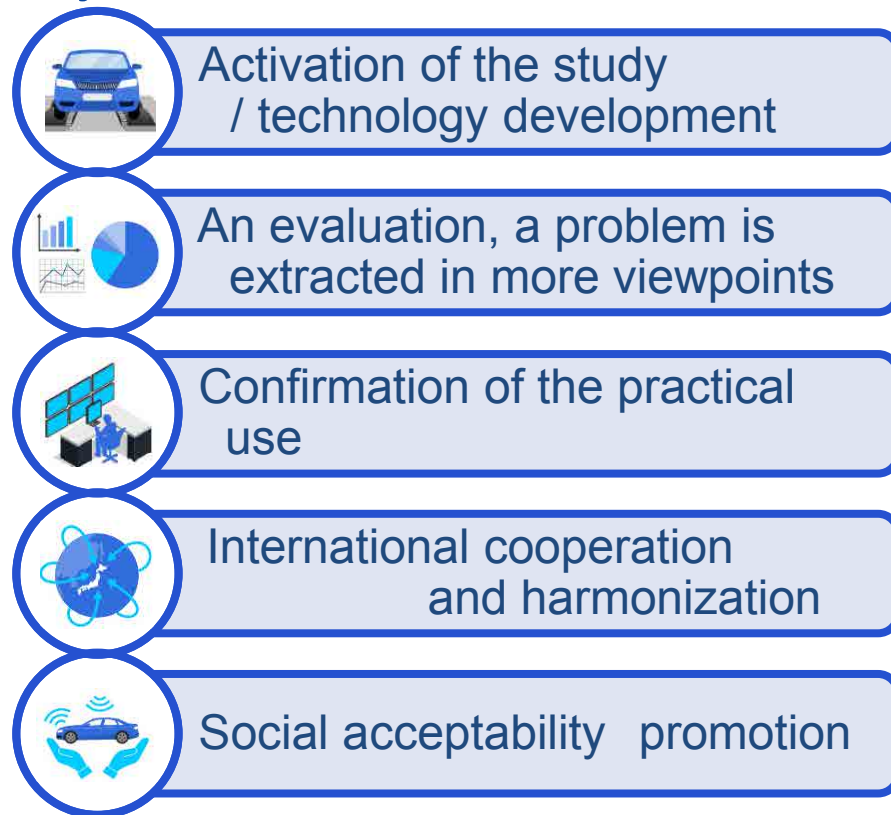
Implementation

Large-scale Field Operational Test (FOT)

« Main themes »



« Objectives »



Large-scale Field Operational Test (FOT)

《Participants》

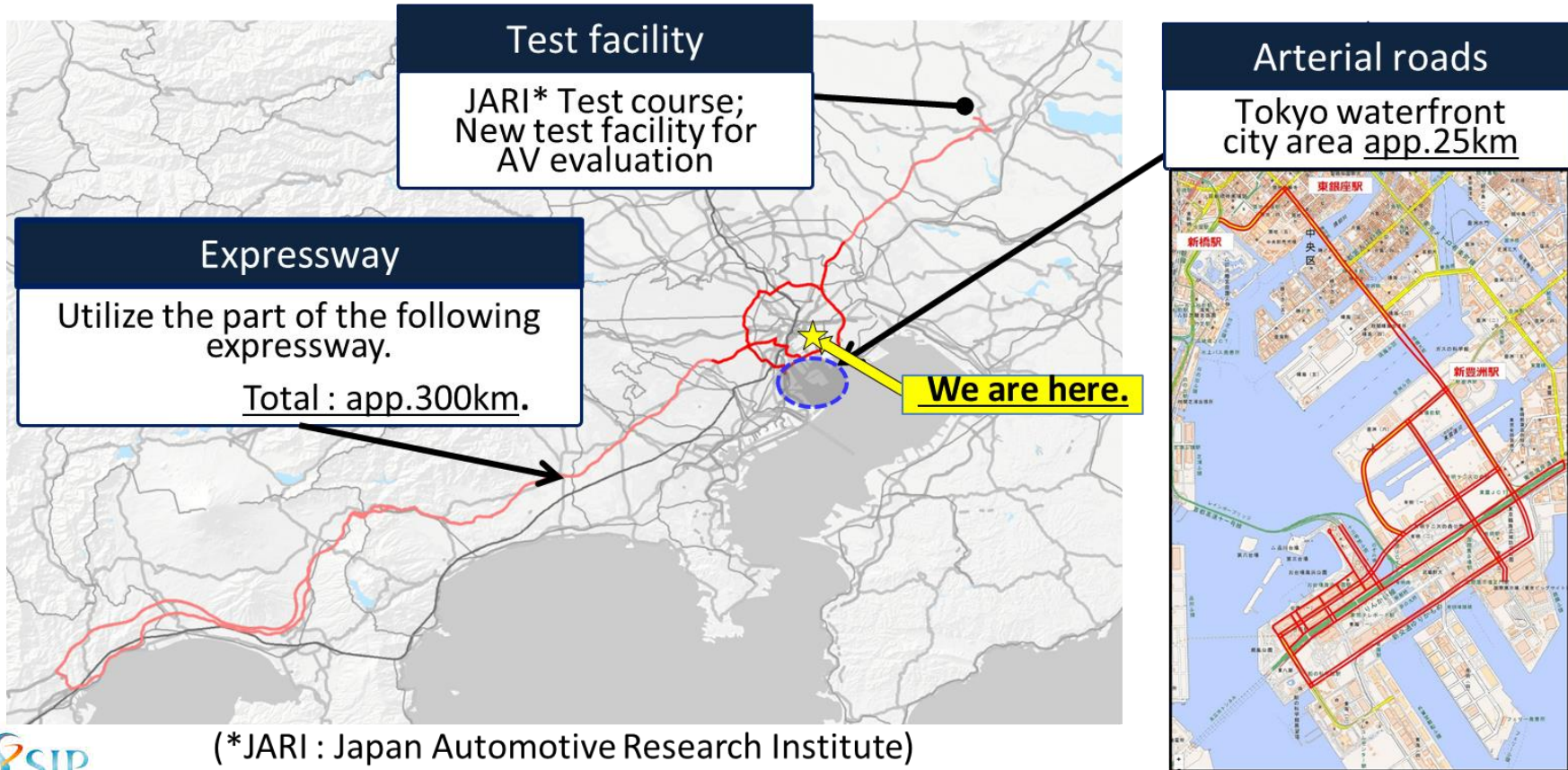


(Each participant brings a vehicle of their own)

《Period》

Oct./2017 ~ Dec./2018

Test Sites



Dynamic Map FOT

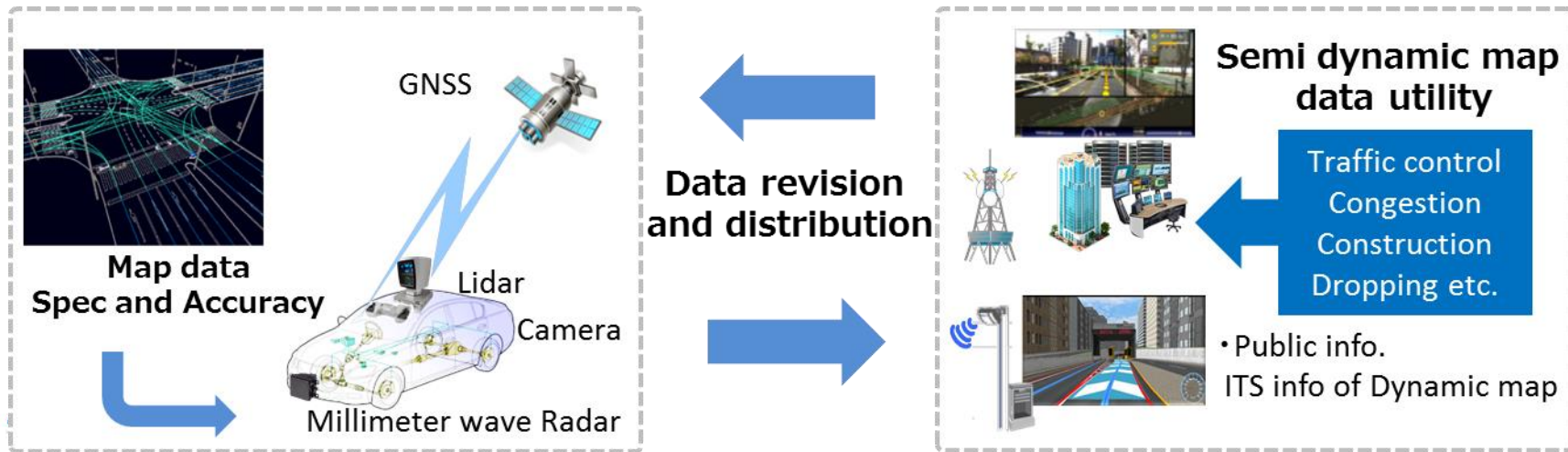
Objective Establish 3D HD digital map spec and Dynamic Map concept

(Step 1) To validate 3D high-definition digital map data.

(Step 2) To validate data collection and distribution method.

(Step 3) To verify the utility of semi dynamic and dynamic information.

✓ Map data is provided by SIP-adus.



Dynamic Map FOT

《Output from FY17 FOT》

- ◆ Preparation and distribution of **3D HD Map** of 758km
- ◆ Confirmation of map features with high accuracy at public road



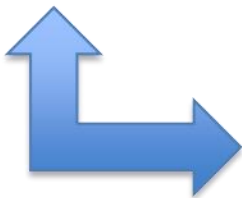
**Consensus formation
of essential features**

《Examples of extracting subject in information freshness》



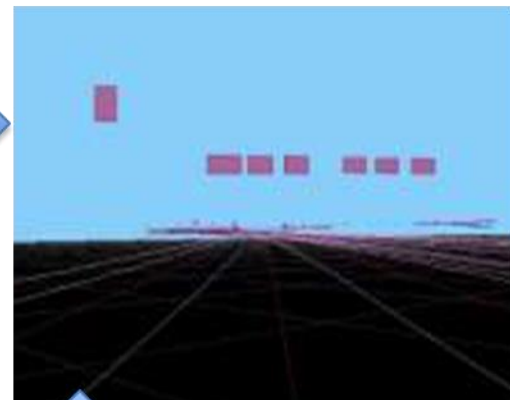
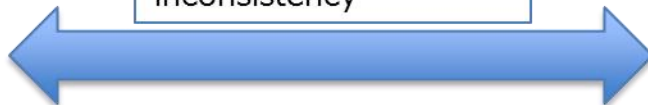
(Participant test image)

③Discovery of
feature removal
after surveying



(Image at survey)

①Indication of data
inconsistency



(Map data)

②Check
consistency with
survey data

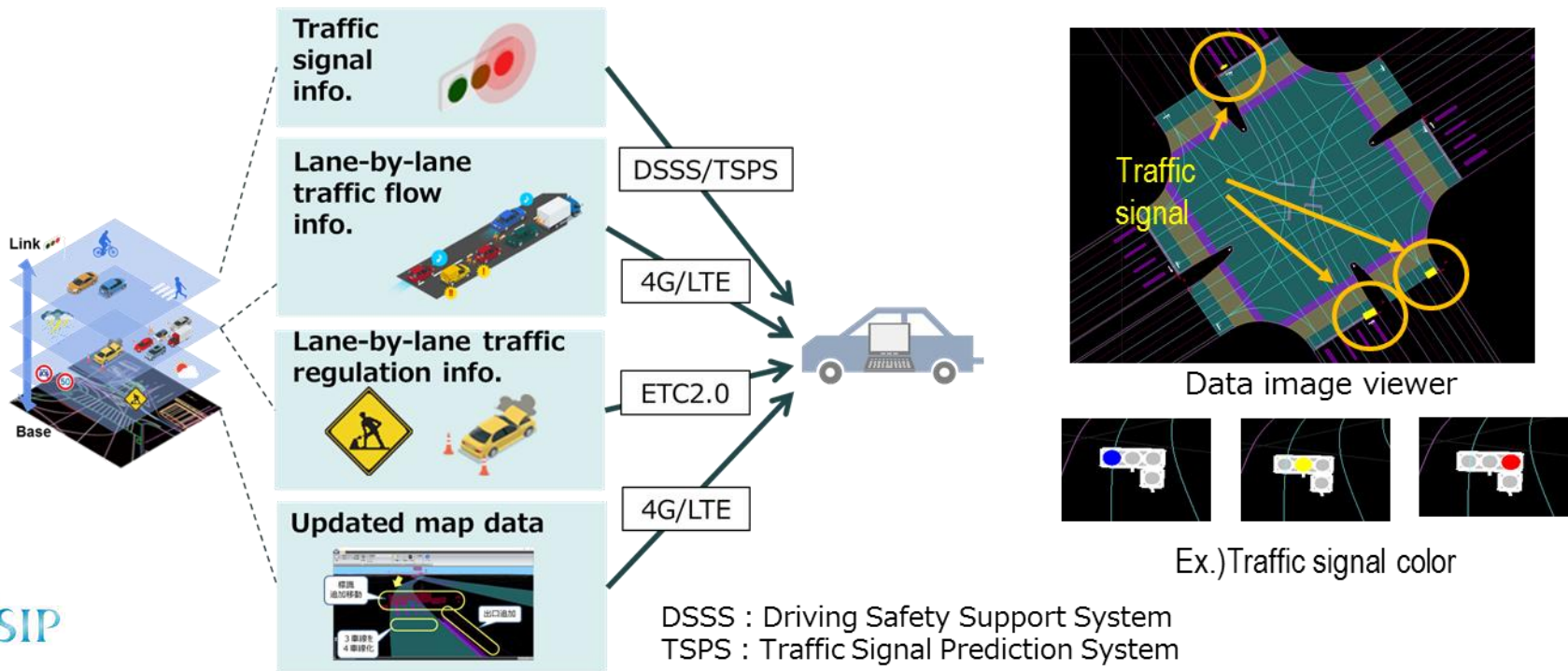


Dynamic Map FOT

《Outline of FY18 FOT》

- ◆ Preparation and distribution of **real-time traffic info** linked to 3D HD Map at public road (~Dec./2018)

➔ Confirmation and establishment of Dynamic Map concept



Human Machine Interface FOT

Objective

Quantification of driver state (readiness) indicator for take-over performance

◆ Development of in-vehicle DMS (Driver Monitoring System)

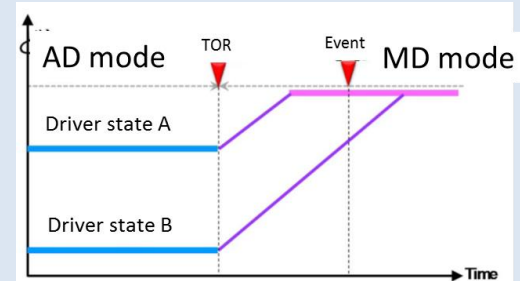


Driver state measurement
@ T/C

- Frequency of the saccadic movements of the eyes, blinking frequency, percent time of forward looking, and Perclos were extracted as metrics of readiness for driver monitoring.

《Output from FOT》

- ◆ Participants collected data by **driving a long distance on the highway** with the vehicle equipped with DMS.
- ◆ **Baseline indicator definition** during manual driving mode by collected data analysis.



Cyber Security FOT

Objective Establish a Cyber Security Evaluation Guideline

Threat Analysis

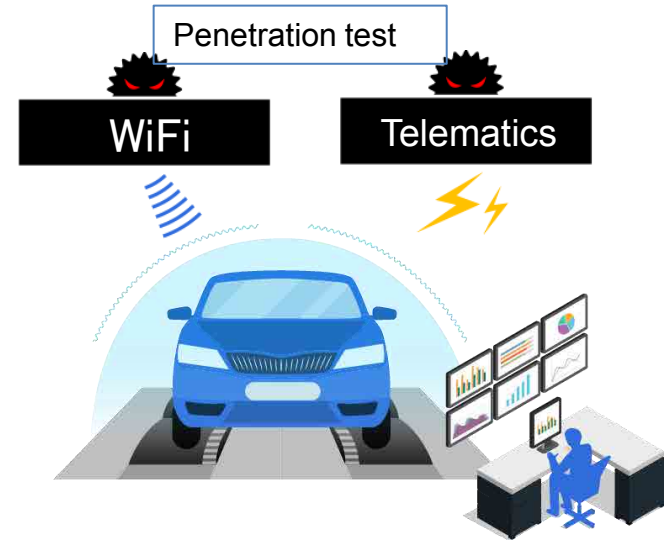
- ◆ Survey of world-wide automated driving systems
- ◆ Already-known threat/vulnerability Info.
- ◆ Risk/Impact analysis



Guideline Development



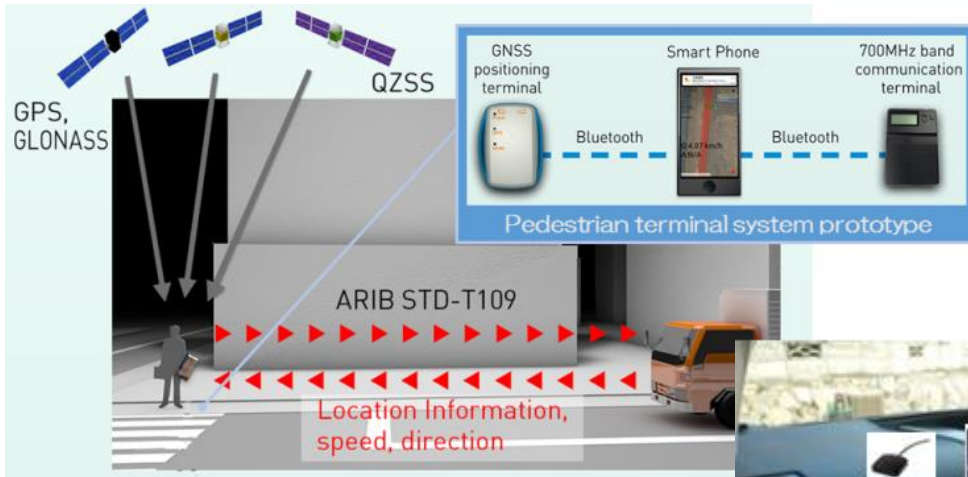
Effectiveness evaluation in Experiment



Pedestrian Accident Reduction FOT

Objective Evaluate V2P communication system performance and effectiveness under real traffic world

- Exchange high accuracy positions and behavior prediction between pedestrians and vehicles for recognition support.



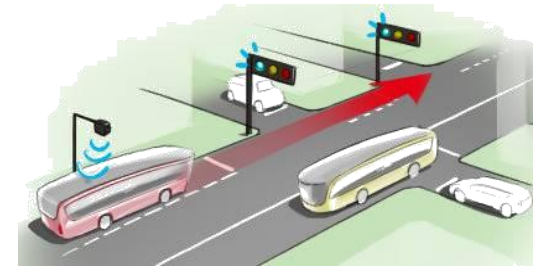
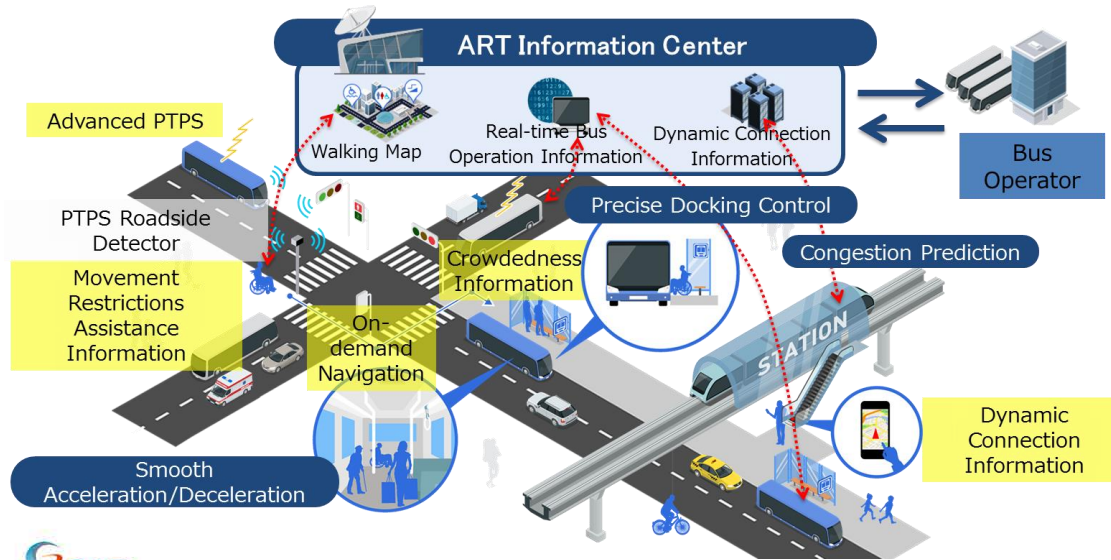
Pre-test @T/C



Next Generation Urban Transportation FOT

Objective Evaluate ART* system performance and effectiveness under real traffic world

- Next generation urban transportation is realized by **ITS technologies** and **automated driving technologies**.



Advanced PTPS
(Public Transportation Priority System)



Precise Docking Control

(*ART: Advanced Rapid Transit)

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1. Large-scale FOT
2. **FOT regional activities**
3. Next Step

FOT regional activities

Automated driving Bus FOT

■ : Test area (3 types of location)



Okinawa



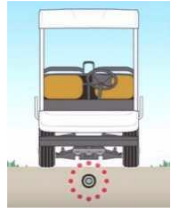
Ishigaki-jima



(Based on the press release of CO)

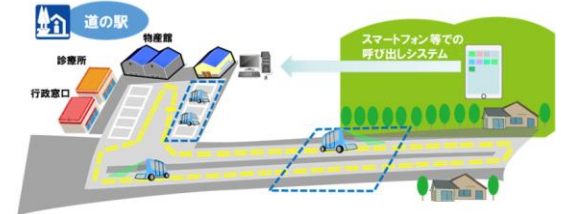
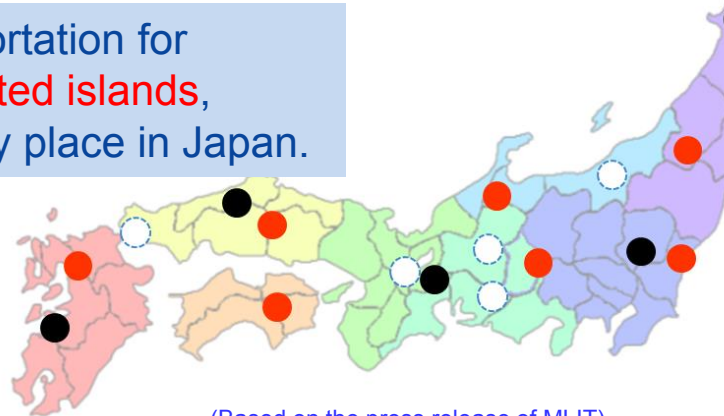
Roadside station-based FOT

● : Regional assignment ● : Public offering ○ : Feasibility study



Electromagnetic induction line

➤ New type public transportation for **depopulated area, isolated islands**, are being tested in many place in Japan.



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1. Large-scale FOT
2. FOT regional activities
3. **Next Step**

FOT of the 2nd phase SIP

**The 2nd phase SIP will start the new FOTs in autumn 2019
in Tokyo Waterfront Area.**

«Objective» **Verification of automated driving technologies
that utilize traffic infrastructure.**

«Period» **Around late 2019 ~ End of FY2022**

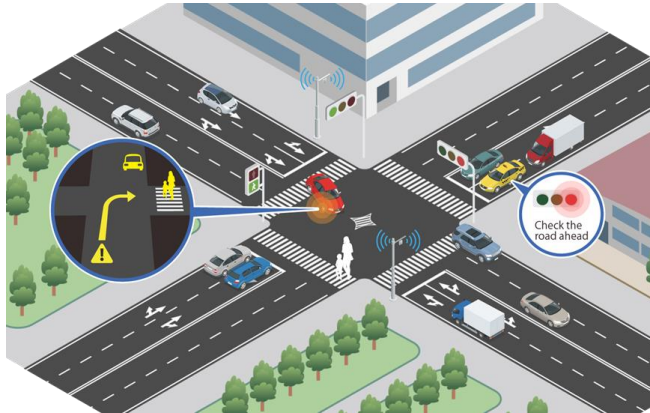
«Participants» **Open to domestic and foreign participants.**
(Automakers/Components manufacturers/Universities/Research institutions
/Venture companies etc.)

FOT of the 2nd phase SIP

«Outline of FOTs (planned)»

Tokyo Waterfront City area

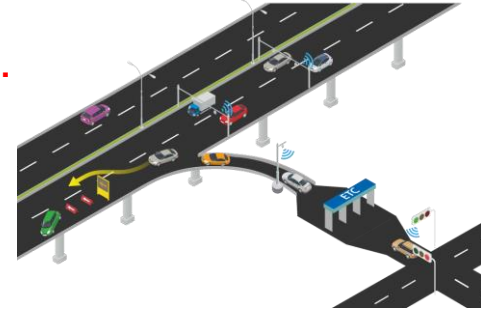
Verification of smooth automated driving technologies using **traffic signal color cycle information**.



*(Public Transportation Priority System)

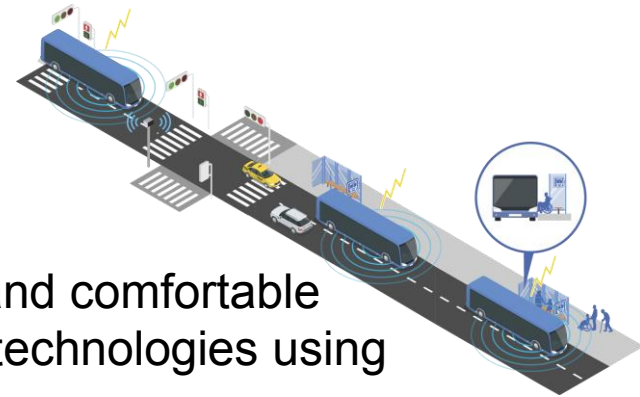
Haneda Airport Connection Expressway

Verification of **ETC gate info.**
/Merging Support info.
/Lane-level traffic regulation info. for automated driving.



Haneda Airport area

Verification of smooth and comfortable automated driving bus technologies using **PTPS***/**Precise docking**
/Acceleration & Deceleration control etc..



FOT of the 2nd phase SIP

«Outline of FOTs (planned)»

Haneda Airport Connection Expressway

Tokyo Waterfront City area

Verification of ETC gate info.
/Meraina Support info.

Veri
drivi
sign

Details of the FOT
and Call for participation will be announced
in Jan. 2019.

Haneda Airport area

Verification of smooth and comfortable
automated driving bus technologies using
PTPS*/Precise docking
/Acceleration & Deceleration control etc..



*(Public Transportation Priority System)

Thank you for your attention

A long-exposure photograph of a city street at night. The image is filled with vibrant, multi-colored light trails from cars and buildings, creating a sense of motion and energy. The colors range from bright yellow and white to deep blues and purples. The perspective is from a low angle, looking down the street towards a vanishing point in the distance. The overall atmosphere is dynamic and futuristic.